

*Please provide the following information, and submit to the NOAA DM Plan Repository.*

**Reference to Master DM Plan (if applicable)**

*As stated in Section IV, Requirement 1.3, DM Plans may be hierarchical. If this DM Plan inherits provisions from a higher-level DM Plan already submitted to the Repository, then this more-specific Plan only needs to provide information that differs from what was provided in the Master DM Plan.*

URL of higher-level DM Plan (if any) as submitted to DM Plan Repository:

**1. General Description of Data to be Managed****1.1. Name of the Data, data collection Project, or data-producing Program:**

2009 Oregon Department of Geology and Mineral Industries (DOGAMI) Lidar: Medford

**1.2. Summary description of the data:**

The Oregon Department of Geology & Mineral Industries (DOGAMI) contracted with Watershed Sciences, Inc. to collect high

resolution topographic lidar data for multiple areas within the State of Oregon. The areas for lidar collection have been designed

as part of a collaborative effort of state, federal, and local agencies in order to meet a wide range of project goals.

The Medford study area was collected April 29 - May 12, 2009 and covers a portion of Jackson County. The total

flown area covers 380 square miles, or 242,915 acres. This data set consists of bare earth and unclassified points. There

are approximately 8 points per square meter over terrestrial surfaces. In some areas of heavy vegetation or forest cover,

there may be relatively few ground points in the lidar data. Elevation values for open water surfaces are not valid elevation

values because few lidar points are returned from water surfaces. Lidar intensity values were also collected.

Original contact information:

Contact Name: Ian Madin

Contact Org: DOGAMI

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**1.3. Is this a one-time data collection, or an ongoing series of measurements?**

One-time data collection

**1.4. Actual or planned temporal coverage of the data:**

2009-04-29 to 2009-05-12

**1.5. Actual or planned geographic coverage of the data:**

W: -123.249957, E: -122.507457, N: 42.497776, S: 42.001276

**1.6. Type(s) of data:**

*(e.g., digital numeric data, imagery, photographs, video, audio, database, tabular data, etc.)*

**1.7. Data collection method(s):**

*(e.g., satellite, airplane, unmanned aerial system, radar, weather station, moored buoy, research vessel, autonomous underwater vehicle, animal tagging, manual surveys, enforcement activities, numerical model, etc.)*

**1.8. If data are from a NOAA Observing System of Record, indicate name of system:****1.8.1. If data are from another observing system, please specify:****2. Point of Contact for this Data Management Plan (author or maintainer)****2.1. Name:**

NOAA Office for Coastal Management (NOAA/OCM)

**2.2. Title:**

Metadata Contact

**2.3. Affiliation or facility:**

NOAA Office for Coastal Management (NOAA/OCM)

**2.4. E-mail address:**

coastal.info@noaa.gov

**2.5. Phone number:**

(843) 740-1202

**3. Responsible Party for Data Management**

*Program Managers, or their designee, shall be responsible for assuring the proper management of the data produced by their Program. Please indicate the responsible party below.*

**3.1. Name:****3.2. Title:**

Data Steward

#### 4. Resources

*Programs must identify resources within their own budget for managing the data they produce.*

##### 4.1. Have resources for management of these data been identified?

##### 4.2. Approximate percentage of the budget for these data devoted to data management (specify percentage or "unknown"):

#### 5. Data Lineage and Quality

*NOAA has issued Information Quality Guidelines for ensuring and maximizing the quality, objectivity, utility, and integrity of information which it disseminates.*

##### 5.1. Processing workflow of the data from collection or acquisition to making it publicly accessible

*(describe or provide URL of description):*

Process Steps:

- 2009-01-01 00:00:00 - The LiDAR data was collected between April 29 and May 12, 2009. The survey used a Leica ALS50 Phase II laser system mounted in a Cessna Caravan 208B. The system was set to acquire greater than or equal to 105,000 laser pulses per second (i.e. 105 kHz pulse rate) and flown at 900 meters above ground level (AGL), capturing a scan angle of plus or minus 14 degrees from nadir. These settings were developed to yield points with an average native density of greater than or equal to 8 points per square meter over terrestrial surfaces. The native pulse density is the number of pulses emitted by the LiDAR system. Some types of surfaces (i.e. dense vegetation or water) may return fewer pulses than the laser originally emitted. Therefore, the delivered density can be less than the native density and lightly variable according to distributions of terrain, land cover, and water bodies. The completed areas were surveyed with opposing flight line side-lap of greater than or equal to 50% (greater than or equal to 100% overlap) to reduce laser shadowing and increase surface laser painting. The system allows up to four range measurements per pulse, and all discernible laser returns were processed for the output dataset. During the LiDAR survey of the study area, a static (1 Hz recording frequency) ground survey was conducted over monuments with known coordinates. After the airborne survey, the static GPS data were processed using triangulation with CORS stations checked against the Online Positioning User Service (OPUS) to quantify daily variance. Multiple sessions are processed over the same monument to confirm the antenna height measurements and reported position accuracy. Multiple DGPS units are used for the ground real-time kinematic (RTK) portion of the survey. To collect accurate ground surveyed points, a GPS base unit is set up over monuments to broadcast a kinematic correction to a roving GPS unit. The ground crew uses a roving unit to receive radio-relayed kinematic corrected positions from the base unit. This method is referred to as real-time kinematic (RTK) surveying and allows precise location measurement (sigma less

than or equal to 1.5 cm (0.6 in)). For the Medford study area, 2661 RTK points were collected.

- 2009-01-01 00:00:00 - 1. Laser point coordinates are computed using the IPAS and ALS Post Processor software suites based on independent data from the LiDAR system (pulse time, scan angle), and aircraft trajectory data (SBET). Laser point returns (first through fourth) are assigned an associated (x, y, z) coordinate along with unique intensity values (0-255). The data are output into large LAS v. 1.1 files; each point maintains the corresponding scan angle, return number (echo), intensity, and x, y, z (easting, northing, and elevation) information. 2. These initial laser point files are too large to process. To facilitate laser point processing, bins (polygons) are created to divide the dataset into manageable sizes (less than 500 MB). Flightlines and LiDAR data are then reviewed to ensure complete coverage of the study area and positional accuracy of the laser points. 3. Once the laser point data are imported into bins in TerraScan, a manual calibration is performed to assess the system offsets for pitch, roll, heading, and mirror scale. Using a geometric relationship developed by Watershed Sciences, each of these offsets is resolved and corrected if necessary. 4. The LiDAR points are then filtered for noise, pits, and birds by screening for absolute elevation limits, isolated points, and height above ground. Each bin is then inspected for pits and birds manually; spurious points are removed. For a bin containing approximately 7.5-9.0 million points, an average of 50-100 points are typically found to be artificially low or high. These spurious non-terrestrial laser points must be removed from the dataset. Common sources of non-terrestrial returns are clouds, birds, vapor, and haze. 5. The internal calibration is refined using TerraMatch. Points from overlapping lines are tested for internal consistency and final adjustments are made for system misalignments (i.e., pitch, roll, heading offsets and mirror scale). Automated sensor attitude and scale corrections yield 3-5 cm improvements in the relative accuracy. Once the system misalignments are corrected, vertical GPS drift is then resolved and removed per flight line, yielding a slight improvement (less than 1 cm) in relative accuracy. At this point in the workflow, data have passed a robust calibration designed to reduce inconsistencies from multiple sources (i.e. sensor attitude offsets, mirror scale, GPS drift) using a procedure that is comprehensive (i.e. uses all of the overlapping survey data). Relative accuracy screening was complete. 6. The TerraScan software suite is designed specifically for classifying near-ground points (Soininen, 2004). The processing sequence begins by removing all points that are not near the earth based on geometric constraints used to evaluate multi-return points. The resulting bare earth (ground) model is visually inspected and additional ground point modeling is performed in site-specific areas (over a 50-meter radius) to improve ground detail. This is only done in areas with known ground modeling deficiencies, such as: bedrock outcrops, cliffs, deeply incised stream banks, and dense vegetation. In some cases, ground point classification includes known vegetation (i.e., understory, low/dense shrubs, etc.) and these points are manually reclassified as non-grounds. Ground surface rasters were developed from triangulated irregular networks (TINs) of ground points.

- 2012-03-01 00:00:00 - The NOAA Office for Coastal Management (OCM) received the files in las format. The files contained LiDAR elevation and intensity measurements. The data were in Oregon Lambert (NAD83), International Feet projection and NAVD88 (Geoid 03) vertical datum. OCM performed the following processing for data storage and Digital Coast provisioning purposes: 1. The data were converted from Oregon Lambert (NAD83), International Feet to geographic coordinates. 2. The data were converted from NAVD88 (orthometric) heights to GRS80 (ellipsoid) heights using Geoid 03. 3. The vertical units of the data were converted from International feet to meters. 4. Elevation outliers were filtered.

**5.1.1. If data at different stages of the workflow, or products derived from these data, are subject to a separate data management plan, provide reference to other plan:**

**5.2. Quality control procedures employed (describe or provide URL of description):**

## 6. Data Documentation

*The EDMC Data Documentation Procedural Directive requires that NOAA data be well documented, specifies the use of ISO 19115 and related standards for documentation of new data, and provides links to resources and tools for metadata creation and validation.*

**6.1. Does metadata comply with EDMC Data Documentation directive?**

No

**6.1.1. If metadata are non-existent or non-compliant, please explain:**

Missing/invalid information:

- 1.6. Type(s) of data
- 1.7. Data collection method(s)
- 3.1. Responsible Party for Data Management
- 4.1. Have resources for management of these data been identified?
- 4.2. Approximate percentage of the budget for these data devoted to data management
- 5.2. Quality control procedures employed
- 7.1. Do these data comply with the Data Access directive?
  - 7.1.1. If data are not available or has limitations, has a Waiver been filed?
  - 7.1.2. If there are limitations to data access, describe how data are protected
- 7.4. Approximate delay between data collection and dissemination
- 8.1. Actual or planned long-term data archive location
- 8.3. Approximate delay between data collection and submission to an archive facility
- 8.4. How will the data be protected from accidental or malicious modification or deletion prior to receipt by the archive?

**6.2. Name of organization or facility providing metadata hosting:**

NMFS Office of Science and Technology

**6.2.1. If service is needed for metadata hosting, please indicate:**

**6.3. URL of metadata folder or data catalog, if known:**

<https://www.fisheries.noaa.gov/inport/item/49905>

**6.4. Process for producing and maintaining metadata**

*(describe or provide URL of description):*

Metadata produced and maintained in accordance with the NOAA Data Documentation Procedural Directive: [https://nosc.noaa.gov/EDMC/DAARWG/docs/EDMC\\_PD-Data\\_Documentation\\_v1.pdf](https://nosc.noaa.gov/EDMC/DAARWG/docs/EDMC_PD-Data_Documentation_v1.pdf)

**7. Data Access**

*NAO 212-15 states that access to environmental data may only be restricted when distribution is explicitly limited by law, regulation, policy (such as those applicable to personally identifiable information or protected critical infrastructure information or proprietary trade information) or by security requirements. The EDMC Data Access Procedural Directive contains specific guidance, recommends the use of open-standard, interoperable, non-proprietary web services, provides information about resources and tools to enable data access, and includes a Waiver to be submitted to justify any approach other than full, unrestricted public access.*

**7.1. Do these data comply with the Data Access directive?**

**7.1.1. If the data are not to be made available to the public at all, or with limitations, has a Waiver (Appendix A of Data Access directive) been filed?**

**7.1.2. If there are limitations to public data access, describe how data are protected from unauthorized access or disclosure:**

**7.2. Name of organization of facility providing data access:**

NOAA Office for Coastal Management (NOAA/OCM)

**7.2.1. If data hosting service is needed, please indicate:**

**7.2.2. URL of data access service, if known:**

<https://coast.noaa.gov/dataviewer/#/lidar/search/where:ID=1171>

<https://noaa-nos-coastal-lidar-pds.s3.amazonaws.com/laz/geoid18/1171/index.html>

**7.3. Data access methods or services offered:**

This data can be obtained on-line at the following URL:

<https://coast.noaa.gov/dataviewer/#/lidar/search/where:ID=1171>

This data set is dynamically generated based on user-specified parameters.

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**7.4. Approximate delay between data collection and dissemination:****7.4.1. If delay is longer than latency of automated processing, indicate under what authority data access is delayed:****8. Data Preservation and Protection**

*The NOAA Procedure for Scientific Records Appraisal and Archive Approval describes how to identify, appraise and decide what scientific records are to be preserved in a NOAA archive.*

**8.1. Actual or planned long-term data archive location:**

*(Specify NCEI-MD, NCEI-CO, NCEI-NC, NCEI-MS, World Data Center (WDC) facility, Other, To Be Determined, Unable to Archive, or No Archiving Intended)*

**8.1.1. If World Data Center or Other, specify:****8.1.2. If To Be Determined, Unable to Archive or No Archiving Intended, explain:****8.2. Data storage facility prior to being sent to an archive facility (if any):**

Office for Coastal Management - Charleston, SC

**8.3. Approximate delay between data collection and submission to an archive facility:****8.4. How will the data be protected from accidental or malicious modification or deletion prior to receipt by the archive?**

*Discuss data back-up, disaster recovery/contingency planning, and off-site data storage relevant to the data collection*

**9. Additional Line Office or Staff Office Questions**

*Line and Staff Offices may extend this template by inserting additional questions in this section.*